

BMI/CS 776

Lecture #18

Pattern matching -  
Locality-sensitive hashing

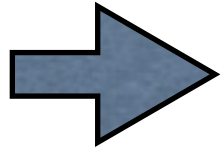
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# Exact vs inexact matching

- Exact matching
  - Good for highly-similar sequences, or for locating highly-conserved short substrings
  - As sequences diverge, exact matching must use shorter seeds, resulting in low specificity
  - Can be done very efficiently - suffix trees/arrays
- Inexact matching
  - Better for diverged sequences
  - Much harder than exact matching

# Inexact matching problem

today



- Given a set  $S$  of sequences
- Find all pairs of  $d$ -mers that differ in at most  $r$  positions
- Or, find all pairs of  $d$ -mers that have edit distance less than  $\epsilon$

# Locality-sensitive hashing

- Problem:
  - Given set of high-dimensional data points
  - Want to find all similar points, or find closest points to a given query point
- Locality-sensitive hashing (Indyk & Motwani, 1998):
  - Hashing scheme with similar points more likely to hash together
  - Randomized algorithm

# $(r, \epsilon)$ -Neighbor problem

- Given:
  - $P$ : set of elements from set  $S$
  - $D$ : distance function on set  $S$
  - $q$ : query element
- Determine whether:
  - exists  $p$  in  $P$  such that  $D(q, p) \leq r$ 
    - return a point  $p'$  such that  $D(q, p') < r(1 + \epsilon)$
  - or all  $p$  in  $P$  have  $D(q, p) \geq r(1 + \epsilon)$

# $(r_1, r_2, p_1, p_2)$ -sensitive hash families

**Definition 1** A family  $\mathcal{H}$  of functions  $h : S \rightarrow U$  is  $(r_1, r_2, p_1, p_2)$ -sensitive for  $D(\cdot, \cdot)$  if  $\forall p, q \in S$

1. if  $p \in \mathcal{B}(q, r_1)$  then  $\mathbb{P}_{\mathcal{H}}[h(q) = h(p)] \geq p_1$
2. if  $p \notin \mathcal{B}(q, r_2)$  then  $\mathbb{P}_{\mathcal{H}}[h(q) = h(p)] \leq p_2$

where  $\mathcal{B}(q, r) = \{p : D(p, q) \leq r\}$

- Useful families have  $p_1 > p_2$  and  $r_1 < r_2$
- The closer the points, the higher the chance of collision via the hash function

# $(r1, r2, p1, p2)$ -sensitive hash family example

$S = H^{d'}$  ( $d'$ -dimensional Hamming cube)

$D(p, q) = d_H(p, q)$  (Hamming distance)

$\mathcal{H}_{d'} = \{h_i : h_i((b_1, \dots, b_{d'})) = b_i, \text{ for } i = 1, \dots, d'\}$

$\mathcal{H}_{d'}$  is  $\left(r, r(1 + \epsilon), 1 - \frac{r}{d'}, 1 - \frac{r(1 + \epsilon)}{d'}\right)$ -sensitive,  $\forall r, \epsilon$

# LSH functions

Choose  $l$  functions  $g_1, \dots, g_l$ , where  $g$  are of the form:

$$g_i(p) = (h_{i_1}(p), h_{i_2}(p), \dots, h_{i_k}(p))$$

where  $h_{i_1}, \dots, h_{i_k}$  chosen at random from  $\mathcal{H}$  with replacement



# LSH preprocessing

**Algorithm** Preprocessing

**Input** A set of points  $P$ ,  
 $l$  (number of hash tables),

**Output** Hash tables  $\mathcal{T}_i, i = 1, \dots, l$

**Foreach**  $i = 1, \dots, l$

    Initialize hash table  $\mathcal{T}_i$  by generating  
    a random hash function  $g_i(\cdot)$

**Foreach**  $i = 1, \dots, l$

**Foreach**  $j = 1, \dots, n$

        Store point  $p_j$  on bucket  $g_i(p_j)$  of hash table  $\mathcal{T}_i$

(Gionis, 1999)

# LSH approximate nearest neighbor

**Algorithm** Approximate Nearest Neighbor Query

**Input** A query point  $q$ ,

$K$  (number of appr. nearest neighbors)

**Access** To hash tables  $\mathcal{T}_i, i = 1, \dots, l$

generated by the preprocessing algorithm

**Output**  $K$  (or less) appr. nearest neighbors

$S \leftarrow \emptyset$

**Foreach**  $i = 1, \dots, l$

$S \leftarrow S \cup \{\text{points found in } g_i(q) \text{ bucket of table } \mathcal{T}_i\}$

Return the  $K$  nearest neighbors of  $q$  found in set  $S$

/\* Can be found by main memory linear search \*/

(Gionis, 1999)

# LSH $(r, \epsilon)$ -Neighbor correctness conditions

$$P' = \{p' : p' \in P, d(q, p') > r_2 = r(1 + \epsilon)\}$$

LSH algorithm solves  $(r, \epsilon)$ -Neighbor problem if both:

**P1** If there exists  $p^*$  s.t.  $p^* \in \mathcal{B}(q, r_1)$ ,  
then  $g_j(p^*) = g_j(q)$  for some  $j = 1, \dots, l$

**P2** The total number of hash table blocks  
referenced by  $q$  and containing only points from  $P'$   
is less than  $cl$ , for some constant  $c$ .

# LSH $(r, \epsilon)$ -Neighbor correctness

**Theorem 1** *For a  $(r_1, r_2, p_1, p_2)$ -sensitive family  $\mathcal{H}$ , if we set  $\rho = \frac{\ln 1/p_1}{\ln 1/p_2}$ ,  $k = \log_{1/p_2}(n/B)$  and  $l = (\frac{n}{B})^\rho$ , then **P1** and **P2** hold with probability at least  $\frac{1}{2} - \frac{1}{e} > 0.132$*



“constant probability” - does not change with input size  $n$

For proof, see (Gionis, 1999)

# Randomized algorithms

- Given an algorithm  $A_1$  that succeeds with probability  $p_1$
- Algorithm  $A_2$ , which runs  $A_1$   $t$  times, succeeds with probability  $p_2 = 1 - (1 - p_1)^t$
- Can make  $p_2$  as big as we like
- For  $t > 32$ , LSH  $(r, \epsilon)$ -Neighbor succeeds with probability  $> 0.99$

# Complexity results

- LSH  $(r, \epsilon)$ -Neighbor used to solve  $\epsilon$ -Nearest Neighbor Search ( $\epsilon$ -NNS) problem
- $O(dn^{1/(1+\epsilon)})$  query time (sublinear!) for all  $\epsilon$
- $O(n^{1+1/(1+\epsilon)} + nd)$  preprocessing time

# LSH for sequence comparison

- Buhler, 2001
- Points are d-mers over some alphabet
- Comparing all d-mers at once, not just one query d-mer against all others
- Hash function  $f$ :
  - pick  $k$  indices  $i_1, \dots, i_k$  from  $\{1, \dots, d\}$
  - $f(s) = (s[i_1], s[i_2], \dots, s[i_k])$

# $(r_1, r_2, p_1, p_2)$ -sensitive property

- If  $s_1$  and  $s_2$  differ by at most  $r_1 = r$  positions then,

$$\mathbb{P}[f(s_1) = f(s_2)] \geq p_1 = \left(1 - \frac{r}{d}\right)^k$$

- If not,  $s_1$  and  $s_2$  differ by at least  $r_2 = r + 1$  positions and

$$\mathbb{P}[f(s_1) = f(s_2)] \leq p_2 = \left(1 - \frac{r+1}{d}\right)^k$$



# LSH-ALL-PAIRS

- Input: Set  $C$  of sequences of total length  $N$
- Output: All pairs of  $d$ -mers that differ by no more than  $r$  substitutions
- Algorithm: Iterate  $\ell$  times:
  - Choose random LSH function (choose  $k$  indices)
  - Partition  $d$ -mers by hash value
  - In each partition, compare all  $d$ -mers, output those that differ in no more than  $r$  positions

# False-negative rate

- Typically set  $\ell$  and  $k$  such that expected false negative rate is sufficiently small (e.g., 0.05)

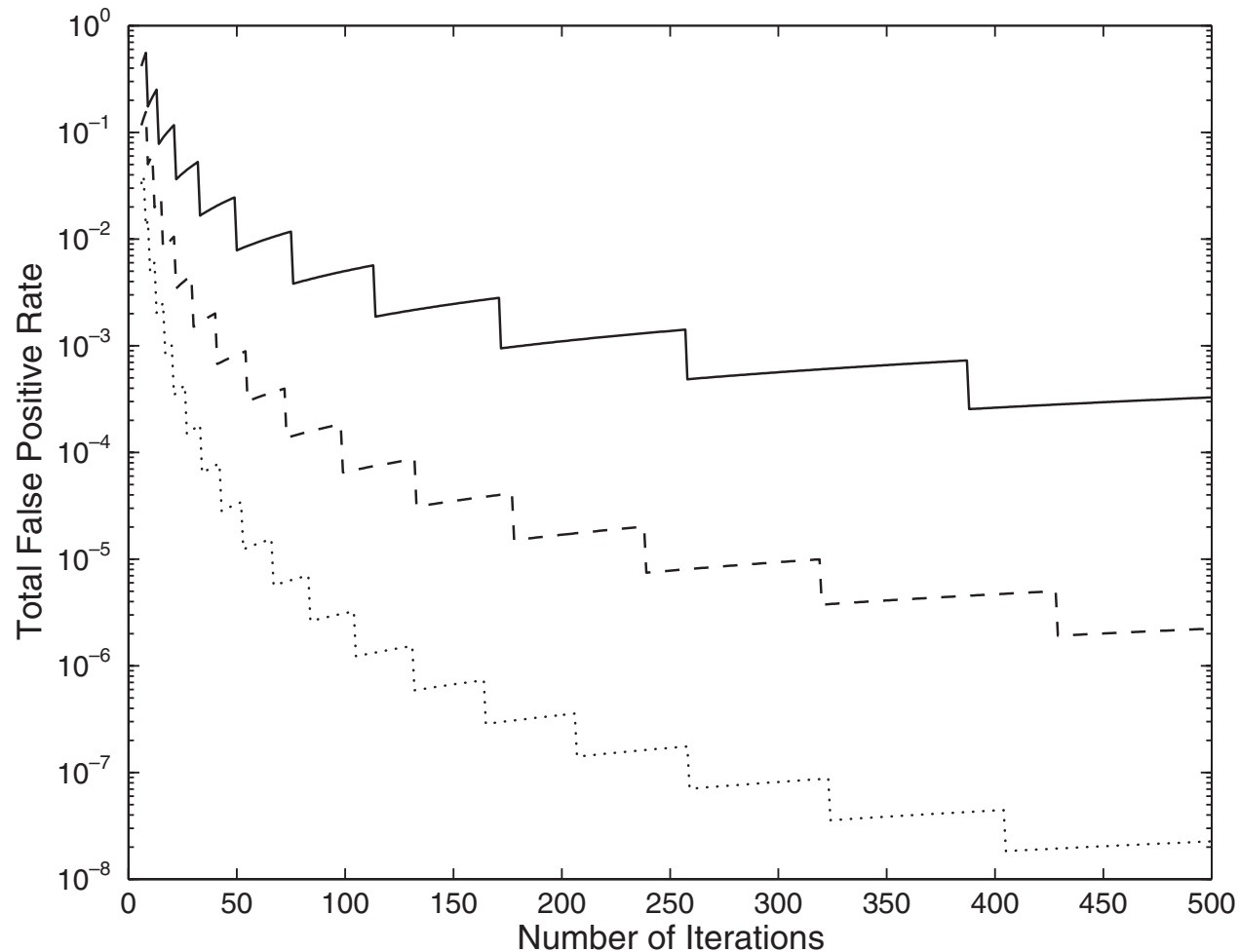
$$\rho_{fn} \leq \left[ 1 - \left( 1 - \frac{r}{d} \right)^k \right]^\ell$$

$$k \leq \frac{\log \left( 1 - \rho_{fn}^{1/\ell} \right)}{\log \left( 1 - \frac{r}{d} \right)}$$

# False positive rate

- False positive rate: fraction of  $d$ -mers that we compare (because they hash to the same value) that are not similar enough
- For two unrelated random  $d$ -mers, assume chance of match at any position is  $\phi$
- Chance that unrelated  $d$ -mers differ by  $t$  substitutions:
$$\beta_{1-\phi,d}(t) = \binom{d}{t} (1 - \phi)^t \phi^{d-t}$$
- False positive rate: 
$$\rho_{fp} = \ell \sum_{t=r+1}^d \beta_{1-\phi,d}(t) \left(1 - \frac{t}{d}\right)^k$$

# Tradeoffs



Fixed  $\rho_{fn} = 0.05$  (i.e.  $k$  is changing).  $d = 75$ .  
Curves for three values of  $r$  (25, 19, 15) Buhler, 2001

# Running time

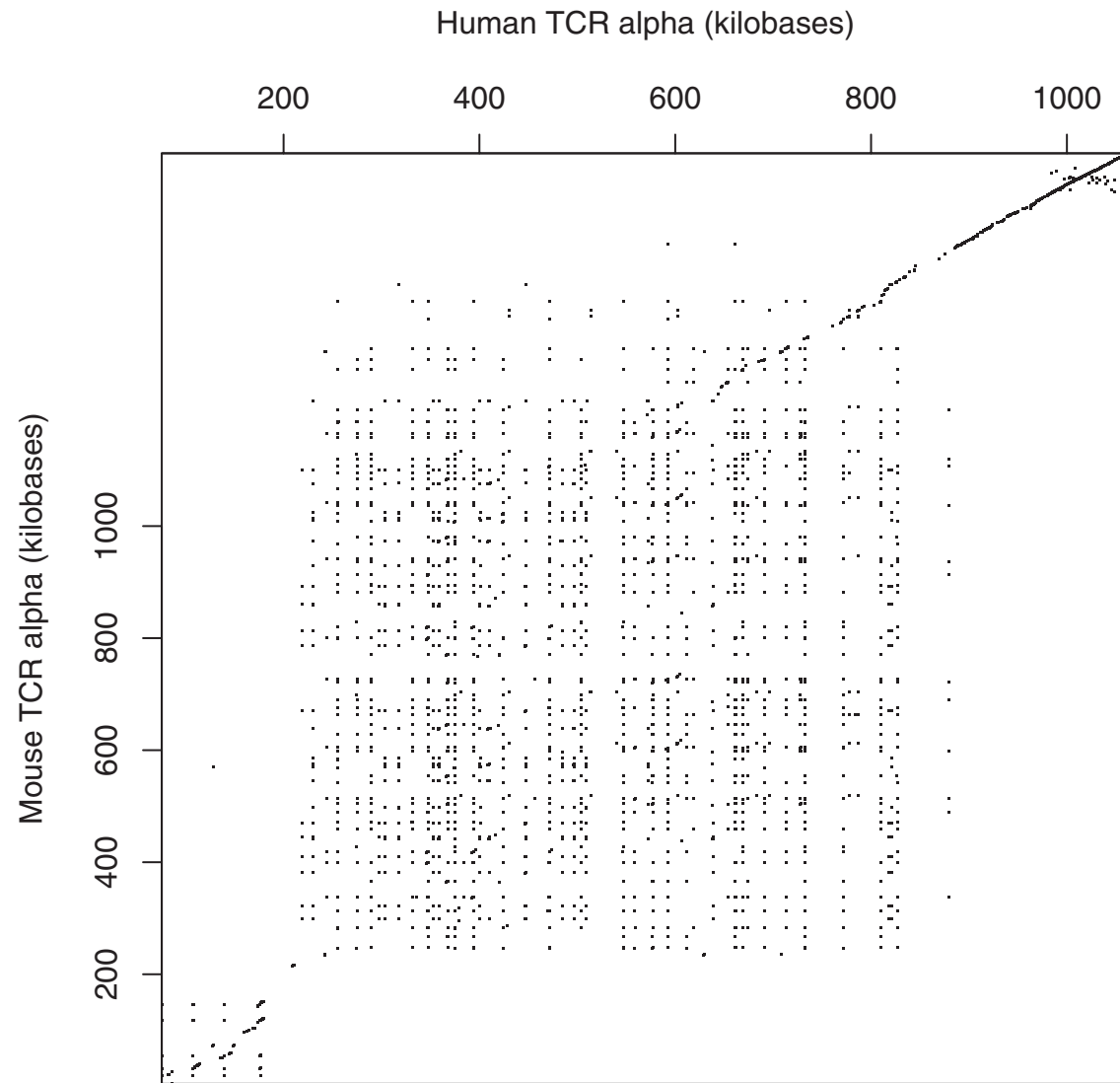
$$O(\ell k N) + O(\rho_{fp} d N^2)$$

hashing/partitioning time

comparison time

- Trick is to balance the two terms
  - $\rho_{fp}$  decreases with increasing  $k$
  - $k$  depends on  $\ell$

# Testing



Buhler, 2001